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robotic arm based on differential gears - *this paper presents the design of an underactuated robotic arm for capturing moving targets with an impact absorbing capability the arm consists of three joints a base joint bj a medial joint mj and a distal joint dj that are driven by two actuators, compact patch antennas on composite printed circuit boards* - *compact patch antennas on composite printed circuit boards in space c min n howland and n r potts printech circuit laboratories 31 35 haltwhistle road south woodham ferrers chelmsford essex cm3 5za uk, strategic counter uas systems* - *auds configurations auds is available in three standard configurations auds deployable system auds field mast system and auds fixed system all systems require just a single operator, the effects of the army 2020 bulk fuel design on decisive* - 1 1

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